No books, no notes. Calculators are allowed

Show all your work in your bluebook. Start each problem on a new page.

- 1. (18 Points) Consider the scalar differential equation $\dot{x} = 4x x^3$.
 - **a**. *Find* the fixed points and *classify* their stability type.
 - **b**. Draw the phase portrait.
- 2. (22 Points) Consider the following system of linear differential equations:

$$\begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = \begin{pmatrix} 3 & -2 \\ 2 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}.$$

- **a**. *Give* the general real solution.
- **b**. *Draw* the phase portrait. Be sure to indicate the direction of the trajectories.
- 3. (26 Points) Consider the following system of nonlinear differential equations:

$$\begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = \begin{pmatrix} y - x^3 \\ x - y \end{pmatrix}.$$

- **a**. *Find* the fixed points. Classify each of them as a stable node, stable focus, saddle, unstable node, etc.
- **b**. Draw the phase portrait using the nullclines and the answer to part (a).
- 4. (34 Points) Consider the following system of nonlinear differential equations:

$$\begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = \begin{pmatrix} y \\ x - x^3 - by \end{pmatrix}.$$

- **a**. Sketch the graph of the potential function V(x) for b = 0.
- **b**. Draw the phase portrait of the system when b = 0.
- **c**. Find a Lyapunov function for b > 0. Verify that it is a Lyapunov function.
- **d**. Sketch the phase portrait of the system when b > 0.