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**Branching Brownian Motion and the Dirichlet  
Problem of a Nonlinear Equation**

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**§1. Introduction**

We consider a simple case of Markov branching processes. Suppose we are given the following data:

- (i) A probability vector  $F = \{p_2, p_3, \dots\}$ ,  $p_i \geq 0$  and  $\sum_{i=2}^{\infty} p_i = 1$ .
- (ii) A nonnegative measurable function  $b$  on  $R^d$ .

Then a  $(b, F)$ -branching Brownian motion on  $R^d$  can be described as follows. At a point  $x \in R^d$ , start an ordinary Brownian motion  $B$ . Choose a random time  $T$  obeying the law

$$(1.1) \quad P\{T > t | B\} = e(t) \stackrel{\text{def}}{=} e^{-\int_0^t b(B_s) ds}$$

and an integral random variable  $M$  obeying the law

$$(1.2) \quad P\{M = n | T, B\} = p_n.$$

At time  $T$ , the Brownian particle splits into  $M$  independent particles and these particles start their own lives according to the law we have just described. The stochastic process (stochastic shower)  $X = \{X_t; t \geq 0\}$  thus obtained has the strong Markov property interpreted in the obvious way. Note that  $X_t$  now stands for a finite or infinite particles moving randomly in  $R^d$  and we write

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$X_t = \{X_t^{(1)}, X_t^{(2)}, \dots, X_t^{(m(t))}\}$ , where  $m(t)$  is the number of particles at time  $t$ . Given a function  $f$  on  $R^d$  and a finite set  $S \in R^d$ , the symbol  $f^*(S)$  stands for the product of the values of  $f$  on  $S$ . Thus if  $m(t)$  is finite,

$$f^*(X_t) = \prod_{i=1}^{m(t)} f(X_t^{(i)})$$

Now suppose  $\|f\|_\infty \leq 1$ , we consider the expression

$$(1.3) \quad u(t, x) = E^x [f^*(X_t); m(t) < \infty].$$

It can be shown easily by the Markov property that function  $u(t, x)$  is the solution of the nonlinear parabolic equation:

$$(1.4) \quad \frac{\partial u}{\partial t} = \frac{1}{2} \Delta u + b[F(u) - u], \quad u(0, \cdot) = f$$

where

$$F(u) = \sum_{i=2}^{\infty} p_n u^n.$$

Thus it is natural to use the  $(b, F)$ -branching Brownian motion to discuss the corresponding Dirichlet problem:

$$(1.5) \quad \begin{cases} \frac{1}{2} \Delta u + b[F(u) - u] = 0, & \text{on } \Omega \\ u = f, & \text{on } \partial\Omega \end{cases}$$

where  $\Omega$  is a bounded domain in  $R^d$ . To explore this connection is the main purpose of the present note. We will denote the boundary value problem (1.5) by  $D(\Omega, F, b; f)$ .

The existence of solution depends on the magnitude of the boundary function. Probabilistically it depends on the speed the Brownian particles accumulate on the boundary. Our discussion centers on the problem of validity of the expression

$$(1.6) \quad u_f(x) = E_x [f^*(X_{\tau_n}); N < \infty]$$

as a solution to the problem (1.5). Let us explain the notation used in (1.6). A particle of the branching Brownian motion will almost surely hit the boundary.

We imagine that each particle is stopped at the first time it hits the boundary. Thus eventually either the process of branching inside  $\Omega$  ceases at a finite time or this process will go on forever. In the former case there are only finitely many particles ending up on the boundary, whereas in the latter case the number of points on the boundary goes to infinity with time. For a fixed time, let  $N_t$  be the number of particles which have already reached the boundary before time  $t$  and let  $N = \lim_{t \rightarrow \infty} N_t$ . The symbol  $X_{\tau_n}$  denotes the set of positions of the particles which eventually reach the boundary. Thus  $X_{\tau_n}$  is finite set on  $\{N < \infty\}$  and (1.6) has a meaning (See [2] for an extensive discussion of Markov branching processes).

As observed in [4], for  $\|f\|_\infty \leq 1$ , the function  $u$  defined in (1.6) is always a solution of  $D(\Omega, F, b; f)$ . We will show that  $u_f$  may represent a solution to the boundary value problem even when  $\|f\|_\infty > 1$ . How large boundary functions can be allowed depends on the domain  $\Omega$  and the branching rate  $b$ . The smaller the domain in area and the smaller the function  $b$  (the slower the branching speed), the larger the boundary function can be allowed (Theorem 3.2). The existence depends essentially on the convergence of the expression (1.6). Let  $q_n(x) = P_x [N = n]$ . Then the problem can be solved for large boundary functions if the probabilities  $q_n(x)$  decreases to zero at least as fast as a geometric progression with a small ratio. In the reverse direction, we show that for any domain, the problem cannot be solved if the boundary function is too large. This requires to show that  $q_n(x)$  no faster than a geometric progression.

In §4, we deal with the case  $\|f\|_\infty \leq 1$ . In this case the uniqueness problem can be completely settled. [5] contains a discussion of this case for constant branching rate  $b$ . Our argument based on the martingale theory is more probabilistic.

Now a few words about basic assumptions in this note. We always assume  $\Omega$  is a domain with finite area. To simplify the discussion we assume that the radius of convergence of  $F$  is infinite. We assume there exist two constants  $c_1$

and  $c_2$  such that  $0 < c_1 \leq b \leq c_2$ . Without assuming any smoothness on the data, by a solution of the problem  $D(\Omega, F, b; f)$  we mean a function  $u$  which is continuous on  $\bar{\Omega}$  and satisfies

$$(1.7) \quad u = G_\Omega[bF(u); b] + H_\Omega(f; b)$$

where

$$G_\Omega[v; b] = - \left[ \frac{\Delta}{2} - b \right]^{-1} v = E_x \left[ \int_0^{\tau_\Omega} e(s) v(B_s) ds \right]$$

and

$$H_\Omega(f; b) = E_x [e(\tau_\Omega) f(B_{\tau_\Omega})].$$

A solution in this sense is classical if the data are sufficiently smooth; see the discussion in [5]. To simplify notation we often write  $\tau = \tau_\Omega$ .

As in [5], the method used here can be applied to Markov branching diffusion of more general type and to the case where  $F$  may depend on the space variables and may take both signs. See also [3] for discussions of related problems from a different point of view.

## §2. Basic Representation Theorem

Under our assumption on  $F$ , we have  $F'(1) < \infty$ . Therefore  $n(t) < \infty$  a.s. for any finite  $t$ . Furthermore, for any bounded function  $f$ , there exists an  $\epsilon > 0$  such that  $f^*(X_t)$  is integrable for  $0 \leq t \leq \epsilon$ . Hence  $u(t, x)$  in (1.3) is well defined as least for small time. These facts can be proved by using formula (7) of [1], p.106.

Let  $u_f$  be defined as in (1.6). For a nonnegative  $f$ , function  $u_f$  is always defined but may be infinite.

**Proposition 2.1.** Suppose that  $f$  is bounded or nonnegative. Then  $u_f$  satisfies (1.7).

*Proof.* This is a simple application of the strong Markov property. Let  $\tau = \tau_\Omega$  as before. We always use  $B$  to denote the base Brownian motion of  $X$ . Recall

that  $T$  is the first splitting time. Using the Markov property at  $\tau \wedge T$ , we have by (1.2)

$$\begin{aligned} u_f(x) &= E_x [E_{X_{\tau \wedge T}}^* [f^*(X_\tau); N < \infty]] \\ &= E_x [f(B_\tau); \tau < T] + E_x [E_{X_\tau}^* [f^*(X_\tau); N < \infty]; \tau \geq T] \\ &= E_x [f(B_\tau); \tau < T] + E_x [F(u(B_\tau)); \tau \geq T]. \end{aligned}$$

(1.7) follows from this identity and (1.1).

Before proving the next proposition, we need a lemma.

**Lemma 2.2.** Let  $u(t, x) = E_x [u^*(B_{\tau \wedge t})]$ . If  $u$  is bounded and satisfies (1.7), then  $u(t, x) = u(x)$ .

*Proof.* Note that a priori we do not know the random variable  $u^*(X_{\tau \wedge t})$  is integrable. But from the remark at the beginning of this section we know it is so for small  $t$ . Thus by the semigroup property, it is sufficient to establish the result for small  $t$ . Split the integral  $E_x [u^*(X_{\tau \wedge t})]$  into three pieces:  $|\tau \leq T|$ ,  $|\tau < \tau|$  and  $|\tau < \tau \wedge t|$ . Using (1.1) and (1.2) and the Markov property,

$$\begin{aligned} (2.1) \quad u(t, x) &= E_x [u(B_{\tau \wedge t})e(\tau)] + E_x [u(B_t)(e(t) - e(\tau)); t < \tau] \\ &\quad + E_x [F(u(t - T, B_T)); T < \tau \wedge t] \\ &= E_x [u(B_{\tau \wedge t})e(\tau \wedge t)] \\ &\quad + E_x \left[ \int_0^{\tau \wedge t} F(u(t - s, B_s))e(s)b(B_s)ds \right]. \end{aligned}$$

On the other hand, from (1.7) we have

$$(2.2) \quad u(x) = E_x [u(B_{\tau \wedge t})e(\tau \wedge t)] + E_x \left[ \int_0^{\tau \wedge t} F(u(B_s))e(s)b(B_s)ds \right].$$

Subtracting (2.2) from (2.1) and using  $|F(u) - F(v)| \leq K|u - v|$ , we obtain

$$e(t, x) \leq K \int_0^t E_x [e(t - s, B_s); s < \tau] ds$$

with  $e(t, x) = |u(t, x) - u(x)|$ . Integrating over  $\Omega$  and using Gronwall's inequality, we see  $e(t, x) \equiv 0$ . The lemma is proved.

**Theorem 2.3.** Suppose  $u$  is a solution of  $D(\Omega, F, b, f)$ . Then

$$\{M_t \stackrel{\text{def}}{=} u^*(B_{\tau \wedge t}); t \geq 0\}$$

is a  $P_x$ -martingale for any  $x \in \Omega$ .

*Proof.* By Proposition 2.1 and Lemma 2.2, the random variable  $M_t$  is integrable. Now for any  $s \leq t$ ,

$$E_x [M_t | \mathcal{F}_{\tau \wedge s}] = E_{x, \tau \wedge s}^x [M_{\tau \wedge (t-s)}] = u^*(X_{\tau \wedge s}) = M_s.$$

Therefore,  $M = \{M_t; t \geq 0\}$  is a  $\mathcal{F}_{\tau \wedge t}$ -martingale.

**Proposition 2.4.** (Minimality of the probabilistic solution) Let  $f \geq 0$  and let  $u$  be a solution of  $D(\Omega, F, b, f)$ . Let  $u_f$  be the probabilistic solution (1.6). Then  $0 \leq u_f \leq u$ .

*Proof.* Follows easily from the preceding proposition. We have

$$\begin{aligned} u(x) &= E_x [u^*(X_{\tau \wedge t})] \geq \lim_{t \rightarrow \infty} E_x [u^*(X_{\tau \wedge t}); N < \infty] \\ &\geq E_x \left[ \lim_{t \rightarrow \infty} u^*(X_{\tau \wedge t}); N < \infty \right] \geq E_x [u^*(X_\tau); N < \infty] \\ &= u_f(x). \end{aligned}$$

### §3. Existence of Solutions

In view of Proposition 2.1, we look for conditions on the boundary function under which the expression (1.6) is meaningful. We use a very simple-minded estimate:

$$(3.1) \quad |u_f(x)| \leq \sum_{n=1}^{\infty} \|f\|_{\infty}^n q_n(x).$$

Here  $q_n(x) = P_x [N = n]$ . Thus the boundedness of  $u_f$  depends on the decreasing rate of the probabilities  $q_n$ . Letting  $f \equiv \alpha$  in (1.7) and comparing coefficients for powers of  $\alpha$ , we see that  $q_n$  satisfies the following recursion formula:

$$(3.2) \quad q_n = G_{\Omega} [b H_n(q_1, \dots, q_{n-1}); b]$$

where  $H_n$ 's are determined by

$$F \left( \sum_{n=1}^{\infty} a_n \xi^n \right) = \sum_{n=2}^{\infty} H_n(a_1, \dots, a_{n-1}) \xi^n,$$

and

$$q_1 = E[e(\tau_{\Omega})].$$

We say that  $F$  terminates at  $m_0$  if  $p_n = 0$  for  $n > m_0$ . We need the following simple lemma, whose proof we omit.

**Lemma 3.1.** (a) Assume that  $F$  terminates. Let sequence  $A_n, n \geq 1$  be defined by  $A_1 = 1$  and  $A_n = H_n(A_1, \dots, A_{n-1})$ . Then the power series  $\sum_{n=1}^{\infty} A_n \xi^n$  has a positive radius of convergence  $r \geq 3 - 2\sqrt{2}$ . (b) Let  $I_n$  be defined by

$$p_{n_0} \left( \sum_{n=1}^{\infty} a_n \xi^n \right) = \sum_{n=2}^{\infty} I_n(a_1, \dots, a_{n-1}) \xi^n.$$

Let  $c > 0$ . Let sequence  $B_n, n \geq 1$  and let defined by  $B_1 = c$  and  $B_n = I_n(B_1, \dots, B_{n-1})$ . Then the power series  $\sum_{n=1}^{\infty} B_n \xi^n$  has a finite radius of convergence.

The following result gives a lower and an upper bound for the probabilities

$$q_n(x).$$

**Proposition 3.2.** (a) Assume that  $F$  terminates at  $m_0$ . There exist a  $K_1$  and a positive  $\gamma$  independent of  $F$  such that for all  $n \geq 1$

$$(3.3) \quad \|q_n\|_{\infty} \leq K_1 \left( \gamma \|b\|_{\infty} |\Omega|^{2/d} \right)^{\frac{n-1}{m_0-1}}.$$

(b) Assume  $\Omega$  is bounded and smooth. There exist positive constants  $K_2$  and  $\beta$  such that for all  $n \geq 1$

$$(3.4) \quad q_n(x) \geq K_2 \beta^{n-1} h(x).$$

Here

$$h = G_{\Omega} [b; b] = 1 - E[e(\tau_{\Omega})].$$

*Proof.* (a) Upper bound. Define  $A_n$  as in the preceding lemma. We prove by induction that

$$(3.5) \quad \|q_n\|_\infty \leq A_n \|h\|_\infty^{\frac{n-1}{m_0-1}}.$$

The inequality holds obviously for  $n = 1$ . To go from  $n - 1$  to  $n$ , we have by (3.2) and the hypothesis that  $F$  terminates at  $m_0$ .

$$\begin{aligned} u_n &= G_\Omega [H_n(q_1, \dots, q_{n-1}); b; b] \\ &\leq \|h\|_\infty^{\frac{n-m_0}{m_0-1}} H_n(A_1, \dots, A_{n-1}) G_\Omega [b; b] \\ &\leq A_n \|h\|_\infty^{\frac{n-1}{m_0-1}}. \end{aligned}$$

This proves (3.5). Now by the preceding lemma there are positive constants  $K_1$  and  $\gamma_1$  such that  $A_n \leq K_1 \gamma_1^n$ . On the other hand we have for some constant universal constant  $\gamma_2$

$$\|h\|_\infty \leq E_x \int_0^{\tau_n} e(s) b(B_s) ds \leq \|b\|_\infty E_x [\tau_n] \leq \gamma_2 \|b\|_\infty |\Omega|^{2/d}.$$

(3.3) follows with  $\gamma = \gamma_1 \gamma_2$ .

(b) Lower bound. Take  $c = \min_{x \in \bar{\Omega}} E_x [e(\tau_\Omega)] > 0$  and define  $B_n$  as in the preceding lemma. We prove by induction that

$$(3.6) \quad q_n(x) \geq B_n \beta_1^{n-1} h(x)$$

where

$$\beta_1 = \min_{x \in \bar{\Omega}} \frac{G_\Omega [h^{m_0} b; b](x)}{h(x)}.$$

$\beta_1 > 0$  because by the smoothness of the domain, both  $G_\Omega [h^{m_0} b; b]$  and  $h$  vanish on the boundary exactly to the first order. Now (3.6) holds for  $n = 1$  by the definition of  $c$ , since  $q_1(x) = E_x [e(\tau_\Omega)]$ . For the induction step, we have

$$\begin{aligned} q_n &\geq G_\Omega [H_n(q_1, \dots, q_{n-1}); b; b] \\ &\geq \beta_1^{n-2} I_n(\beta_1, \dots, \beta_{n-1}) G_\Omega [h^{m_0} b; b] \\ &\geq B_n \beta_1^{n-1} h \end{aligned}$$

Now by part (b) of the preceding lemma, there exist  $K_2$  and  $\beta_2$  such that  $B_n \geq K_2 \beta_2^n$ . (3.4) follows with  $\beta = \beta_1 \beta_2$ .

The following results follow immediately from the lower and upper bounds and Proposition 2.1 and 2.4.

**Theorem 3.3.** (i) Assume that  $F$  terminates at  $m_0$ . There exists a constant  $\gamma$  independent of  $F$  such that the problem  $D(\Omega, F, b; f)$  has a solution if

$$\|f\|_\infty < \left( \gamma \|b\|_\infty |\Omega|^{2/d} \right)^{-\frac{m_0-1}{m_0}}.$$

(ii) Assume  $\Omega$  is bounded and smooth. There exists a constant  $\beta = \beta(\Omega, F, b)$  such that the problem has a solution if  $\|f\|_\infty < \beta$  and has no positive bounded solution if  $f > \beta$ .

#### §4. The case $\|f\|_\infty \leq 1$

In this section a solution means a solution with  $\|u\|_\infty \leq 1$ . Define

$$(4.1) \quad \lambda = \lambda_1(b, \Omega) \stackrel{\text{def}}{=} \inf_{v|_{\partial\Omega=0}} \frac{\int_\Omega |\nabla v|^2}{\int_\Omega b v^2}.$$

The infimum is attained by a positive continuous function  $\phi$  vanishing on the boundary in the sense that for any continuous  $v$  vanishing on the boundary

$$(4.2) \quad \int_\Omega b v^2 \geq \frac{\lambda}{2} \int_\Omega b v G_\Omega(bv)$$

and

$$(4.3) \quad \phi = \frac{\lambda}{2} G_\Omega(b\phi).$$

Here  $G_\Omega = (-\Delta/2)^{-1}$  is the Green operator of  $\Omega$  with Dirichlet boundary condition. Let

$$\alpha = F'(1) - 1 - \frac{1}{2} \lambda_1(b, \Omega).$$

The following results can be established. Let

$A(t, E)$  = the number of particles in  $E \subset \Omega$  at time  $t$ .

We have

$$(4.4) \quad E_x [A(t, E)] = e^{\beta t} \psi(x) \int_E \psi + o(e^{\beta t})$$

where  $\beta$  is the first eigenvalue of  $\Delta/2 + [F'(1) - 1]b$ :

$$(4.5) \quad \beta = - \inf_{v|_{\partial\Omega}=0} \frac{\frac{1}{2} \int_{\Omega} |\nabla v|^2 - [F'(1) - 1] \int_{\Omega} b v^2}{\int_{\Omega} v^2}$$

and  $\psi$  is its normalized eigenfunction. Furthermore, let

$$\mu(E) = \frac{\int_E \psi}{\int_{\Omega} \psi}.$$

Then there is a sequence  $t_n \rightarrow \infty$  such that for any  $x \in \Omega$

$$(4.6) \quad P_x \left[ \frac{A(t_n, E)}{A(t_n, \Omega)} \rightarrow \mu(E) \mid N = \infty \right] = 1.$$

Both (4.4) and (4.6) can be proved by eigen-expansion, starting from (1.4) (cf. [5]). We also notice that  $\alpha$  and  $\beta$  always take the same sign. This is an immediate consequence of the variational characterizations (4.1) and (4.5), the definition of  $\alpha$  and the lower bound of  $b$ .

**Theorem 4.1.** *Suppose  $u$  is a solution of  $D(\Omega, F, b; f)$ ,  $\|u\|_{\infty} \leq 1$  but  $u \neq 1$ . Then it is the unique solution with such property.*

*Proof.* By the assumption, there must be a set  $E$  of positive measure on which  $|u| \leq \epsilon < 1$ . From Theorem 2.3,

$$(4.7) \quad u(x) = E_x[u(B_{r_n t}); N < \infty] + E_x[u(X_{r_n t}); N = \infty].$$

If  $P_x[N = \infty] = 0$ , the second term on the right side is zero. Otherwise using (4.6), we obtain

$$|E_x[u(B_{r_n t}); N = \infty]| \leq E_x[\epsilon^{A(t_n, E)}; N = \infty] \rightarrow 0.$$

The uniqueness follows then by taking limit in (4.7).

It follows from the theorem that the boundary value problem has exactly one solution if  $\|f\|_{\infty} \leq 1$  but  $f \neq 1$  and at most two solutions if  $f \equiv 1$ . The case  $f \equiv 1$  is critical because 1 is the root of  $F(u) - u = 0$ . The case  $b = \text{const.}$  of the following result was discussed in [5].

**Theorem 4.2.** *If  $\alpha \leq 0$  then  $u \equiv 1$  is the unique solution of  $D(\Omega, F, b; 1)$ , and  $N < \infty$  a.s. If  $\alpha > 0$  then the extinction probability*

$$u_1(x) = P_x[N < \infty]$$

*is the only other solution of the problem and  $0 < u_1 < 1$ .*

*Proof.* (a)  $\alpha \leq 0$ . Assume  $u$  is a solution. Let  $v = 1 - u$ . If  $v \neq 0$ , we have by (1.7) and  $F(1 - v) - 1 > vF'(1)$ ,

$$v = G_{\Omega}[b(1 - v) - bF(1 - v)] < -F'(1)G_{\Omega}(bv).$$

Multiply both sides by  $v$  and integrate. Using (4.2), we have

$$\alpha \int_{\Omega} b v^2 > 0,$$

a contradiction. Therefore  $v \equiv 0$ .

Here is an alternative proof. By (4.7), it is enough to show  $P_x[N < \infty] = 1$  for all  $x \in \Omega$ . As mentioned above,  $\alpha \leq 0$  is equivalent to  $\beta \leq 0$ . Thus by (4.4) we see that  $E_x[A(t, \Omega)] \leq M$  for a constant  $M$ . On the other hand, since  $b$  is bounded from above, we can show that with probability one either  $A(t, \Omega) \rightarrow 0$  or  $\infty$  as  $t \rightarrow \infty$  (cf. [4]). Consequently we must have  $A(t, \Omega) \rightarrow 0$ , a.s., which is equivalent to  $N < \infty$ , a.s.

(b)  $\alpha > 0$ . By Theorem 4.1, we need only prove the assertion  $0 < u_1 < 1$ . Let  $v = 1 - \epsilon\phi$ , where  $\phi$  is the first eigenfunction; see (4.3).  $u_1 < 1$  is implied by the assertion that

$$\left\{ Q_t \stackrel{\text{def}}{=} v^*(X_{r_n t}); t \geq 0 \right\}$$

is a  $P_x$ -supermartingale for small  $\epsilon$ . For then we have

$$\begin{aligned} 1 > v(x) &\geq E_x[v(X_{r_n t})] \geq E_x \left[ \lim_{t \rightarrow \infty} v(X_{r_n t}); N < \infty \right] \\ &= P_x[N < \infty] = u_1(x). \end{aligned}$$

To show that  $Q$  is a supermartingale, all we need is

$$(4.8) \quad v(t, x) \stackrel{\text{def}}{=} E_x[v(X_{r_n t})] \leq v(x).$$

We have as in (2.1)

$$(4.9) \quad v(t, x) = E_x [v(B_{\tau \wedge t})e(\tau \wedge t)] \\ + E_x \left[ \int_0^{\tau \wedge t} F(v(t-s, B_s))h(B_s)e(s)ds \right].$$

But instead of (2.2), we have by (4.3)

$$(4.10) \quad v(x) = E_x [v(B_{\tau \wedge t})e(\tau \wedge t)] \\ + E_x \left[ \int_0^{\tau \wedge t} \left( \frac{1}{2} \lambda (1 - v(B_s)) - v(B_s) \right) e(B_s)h(B_s)ds \right].$$

Let  $\delta = \epsilon \|\phi\|_\infty$ . Choose  $\epsilon$  so that  $F'(1 - \delta) - 1 - \frac{\lambda}{2} > 0$ . Then we have  $F(v) \leq 1 - (1 - v)F'(1 - \delta)$ . Now subtracting (4.10) from (4.9) we obtain

$$\epsilon(t, x) \leq F'(1 - \delta) E_x \left[ \int_0^{\tau \wedge t} \epsilon(t-s, B_s)h(B_s)e(s)ds \right].$$

where  $\epsilon(t, x) = \max\{v(t, x) - v(x), 0\}$ . From this it follows that  $\epsilon(t, x) \equiv 0$  (see the end of the proof of Lemma 2.2).

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